

Kinematics: $v_x = \frac{dx}{dt}$ $a_x = \frac{dv_x}{dt}$ $v_{xf} = v_{xi} + a_x \Delta t$ $x_f = x_i + v_{xi} \Delta t + \frac{1}{2} a_x \Delta t^2$
 $v_{xf}^2 = v_{xi}^2 + 2a_x(x_f - x_i)$ $a_{rad} = \frac{v^2}{r}$ $\vec{v}_{PA} = \vec{v}_{PB} + \vec{v}_{BA}$ $T = \frac{2\pi r}{v}$ $f = 1/T$

Forces and Potentials: $\sum \vec{F}_i = m\vec{a}$ $f_s \leq \mu_s n$ $f_k = \mu_k n$ $F_s = -k(x - x_R)$
 $F_g = \frac{GM_1 M_2}{r^2}$ $GMT^2 = 4\pi^2 r^3$

Rotation: $\omega = \frac{d\theta}{dt}$ $\alpha = \frac{d\omega}{dt}$ $v = \omega r$ $a_{tan} = \alpha r$ $a_{rad} = \omega^2 r$ $\omega = 2\pi f$
 $\theta_f = \theta_i + \omega_i \Delta t + \frac{1}{2} \alpha \Delta t^2$ $\omega_f = \omega_i + \alpha \Delta t$ $\omega_f^2 = \omega_i^2 + 2\alpha(\theta_f - \theta_i)$ $\tau = rF \sin \phi$
 $I = \sum_i m_i r_i^2$ $Mx_{cg} = m_1 x_1 + m_2 x_2 + \dots = \sum_i m_i x_i$ $\sum \tau_{ext} = I\alpha$

Momentum: $\vec{p} = m\vec{v}$ $L = rp \sin \phi = r_{\perp} p$ (particle) $L = I\omega$ (rigid body)

Work-Energy: $W = \vec{F} \cdot \vec{r}$ $P = \frac{\Delta E}{\Delta t}$ $U_g = mgy$ $U_s = \frac{1}{2} kx^2$ $K = \frac{1}{2} mv^2$
 $K = \frac{1}{2} I\omega^2$ $K = \frac{1}{2} MV_{cm}^2 + \frac{1}{2} I_{cm}\omega^2$

Oscillations: $F = -kx$ $x = A \cos(2\pi ft + \phi)$ $\omega = 2\pi f$ $T = \frac{1}{f}$ $f = \frac{1}{2\pi} \sqrt{k/m}$
 $f = \frac{1}{2\pi} \sqrt{g/L}$ $E = \frac{1}{2} kA^2$ $v_{max} = 2\pi f A$ $a_{max} = (2\pi f)^2 A$

Fluids: $\rho = M/V$ $p = F/A$ $p = p_{atm} + \rho gh$ $F_B = \rho_f V_{disp} g$ $A_1 v_1 = A_2 v_2$
 $p_1 + \frac{1}{2} \rho v_1^2 + \rho g y_1 = p_2 + \frac{1}{2} \rho v_2^2 + \rho g y_2$ $Q = v_{avg} A = \frac{(p_1 - p_2) \pi r^4}{8\eta L}$

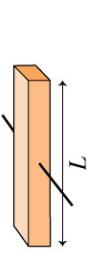
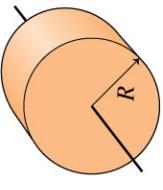
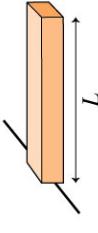
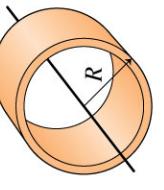
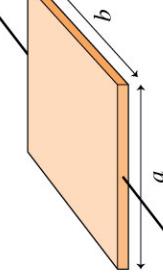
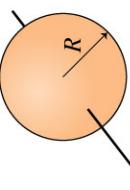
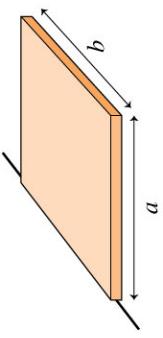
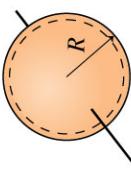
Thermodynamics: $T_K = T_C + 273.15$ $E_{th} = \bar{K}_{tr} = \frac{3}{2} N k_B T$ $W = \int_{V_i}^{V_f} p dV$
 $Q = nC_V \Delta T$ $Q = nC_p \Delta T$ $C_V = \frac{3}{2} R$ $C_p = C_V + R$ $Q = W + \Delta E_{th}$
 $Q = mc \Delta T$ $Q = \pm mL$ $pV = nRT = Nk_B T$ $e = \frac{|W|}{|Q_H|}$ $e_{max} = 1 - \frac{T_C}{T_H}$
 $COP = \frac{|Q_C|}{|W|}$ $COP_{max} = \frac{T_C}{T_H - T_C}$

Vectors: $A_x = A \cos \theta$ $A_y = A \sin \theta$ $A = \sqrt{A_x^2 + A_y^2}$ $\tan \theta = \frac{A_y}{A_x}$
 $\vec{A} \cdot \vec{B} = AB \cos \phi_{AB}$ $\vec{A} \cdot \vec{B} = A_x B_x + A_y B_y + A_z B_z$ $\vec{A} \times \vec{B} = \hat{n} AB \sin \phi_{AB}$

Math: $ax^2 + bx + c = 0$ $x = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a}$ $(1+x)^n \approx 1 + nx$ for $x \ll 1$
 $A = 4\pi r^2$ $V = \frac{4}{3}\pi r^3$

Constants: $g = 9.8 \text{ m/s}^2$ $G = 6.67 \times 10^{-11} \text{ Nm}^2/\text{kg}^2$ $R_{Earth} = 6.37 \times 10^6 \text{ m}$
 $M_{Earth} = 5.98 \times 10^{24} \text{ kg}$ $M_{Sun} = 1.99 \times 10^{30} \text{ kg}$ $c = 2.998 \times 10^8 \text{ m/s}$
 $T_z = -273.15^\circ \text{C}$ $1 \text{ atm} = 1.013 \times 10^5 \text{ N/m}^2 = 101.3 \text{ kPa}$ $\rho_{water} = 1000 \text{ kg/m}^3$
 $k_B = 1.38 \times 10^{-23} \text{ J/K}$ $N_A = 6.022 \times 10^{23}$ $R = 8.3145 \text{ J/mol} \cdot \text{K}$
 $v_{sound} = 343 \text{ m/s}$ $1 \text{ eV} = 1.602 \times 10^{-19} \text{ J}$

TABLE 7.1 Moments of inertia of objects with uniform density and total mass M

Object and axis	Picture	I	Object and axis	Picture	I
Thin rod (of any cross section), about center		$\frac{1}{12}ML^2$	Cylinder or disk, about center		$\frac{1}{2}MR^2$
Thin rod (of any cross section), about end		$\frac{1}{3}ML^2$	Cylindrical hoop, about center		MR^2
Plane or slab, about center		$\frac{1}{12}Ma^2$	Solid sphere, about diameter		$\frac{2}{5}MR^2$
Plane or slab, about edge		$\frac{1}{3}Ma^2$	Spherical shell, about diameter		$\frac{2}{3}MR^2$